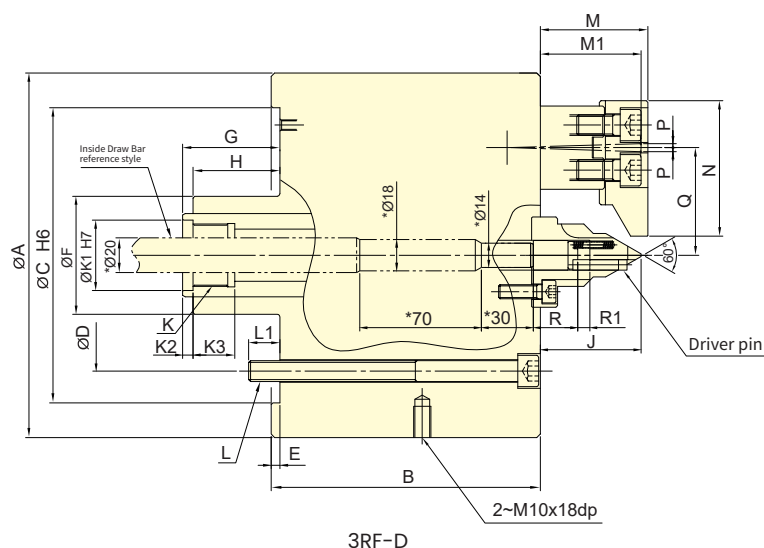
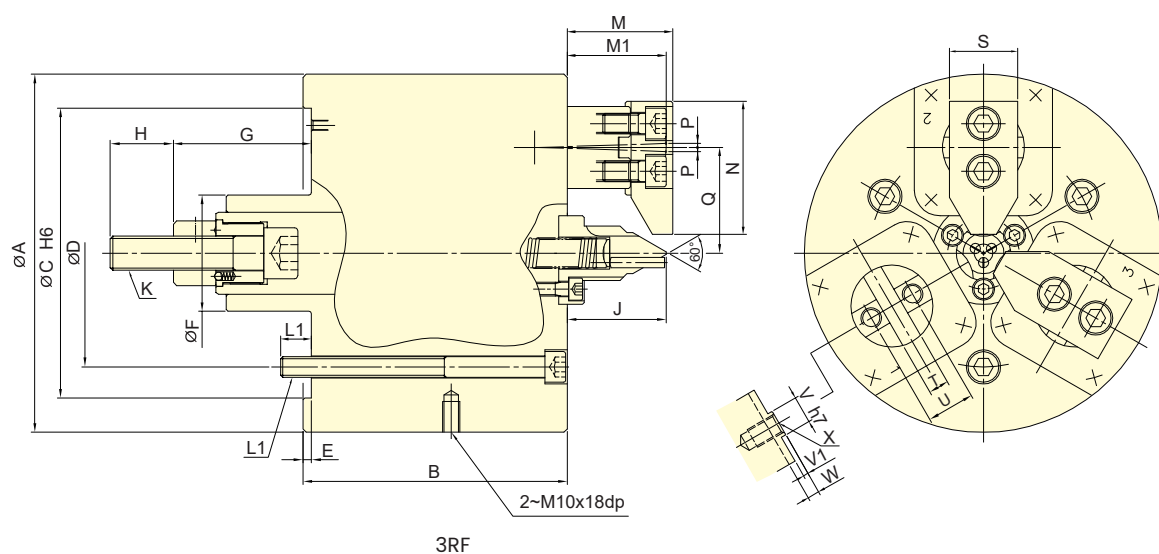




- The workpiece compensation of eccentric is 1mm, fixed position for the center, swing and grasp the workpiece to three jaw.
- Second machining can be performed without reversing the workpiece, thus significantly reducing setup time.
- With compensating jaws clamping, the Rough and precision machining can be carried out.
- With sealed design, the maintenance costs can be reduced.
- Can be paired with double-rod rotary cylinder (3RF-D type).
- The driver pin thrust can be controlled by the pressure of the rotary cylinder (3RF-D type).



Note: The dimensions marked [*] are the dimensions of the inside Draw Bar , Please don't change it.

Subject to technical changes

SPECIFICATIONS

Model	Chucking Dia.	Jaw stroke (Dia.)	Chucking Dia. Max.	Chucking Dia. Min.	Max. D.B. pull	Max. clamping force	Max. speed	Moment of inertia	Weight	Matching cyl.	Compensation
	mm	mm	mm	mm	kN (kgf)	kN (kgf)	min ⁻¹ (r.p.m.)	kg · m ²	kg		mm
3RF-08	43.5	9.4	70	18	39.2 (4000)	39.2 (4000)	4000	0.15	30	RS-1250	1
3RF-08D	43.5	9.4	70	18	39.2 (4000)	39.2 (4000)	4000	0.15	30	RDL-160S	1

DIMENSIONS

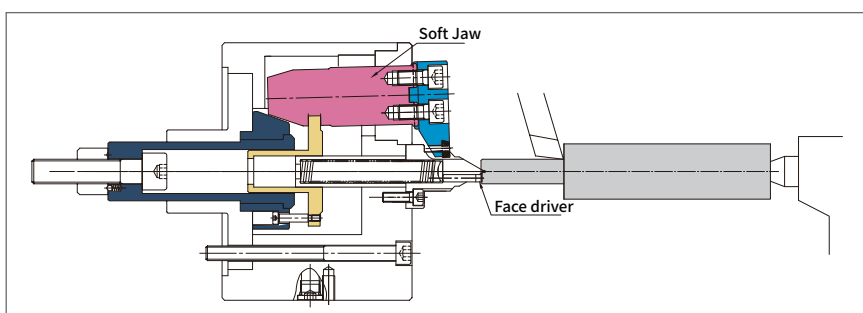
Model	A	B	C (H6)	D	E	F	G max.	G min.	H	J	K	K1 (H7)	K2	K3	L	L1
3RF-08	210	155	170	133.4	5	68	123	79.5	37	58	M20x2.5	-	-	-	3~M12	18
3RF-08D	210	155	170	133.4	5	68	98	54.5	50	58	M36x1.5	40.5	6	24	3~M12	18

Model	M	M1	N	P	Q	R	R1 max.	R1 min.	S	T(H7)	U	V	V1	W	X
3RF-08	62	58	78	2.35	62	-	-	-	40	12	28	16	3	7	M12
3RF-08D	62	58	78	2.35	62	25.5	7	0	40	12	28	16	3	7	M12

APPLICATION NOTES

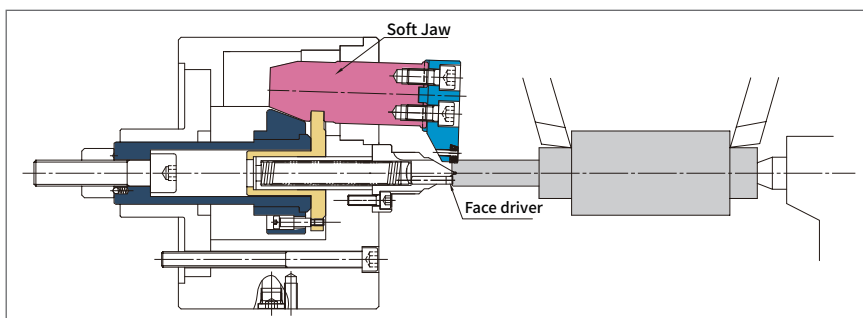
1.Clamping diameter machining

The compensating jaws are retracted. The workpiece is clamped between chuck center and tailstock center. Additionally, it is driven by the face driver.



2.Rough machining

With compensating jaws clamping, the rough machining can be carried out.



3.Finish machining

Additionally, it is driven by the face driver. The entire workpiece can be machined with precise concentricity.

