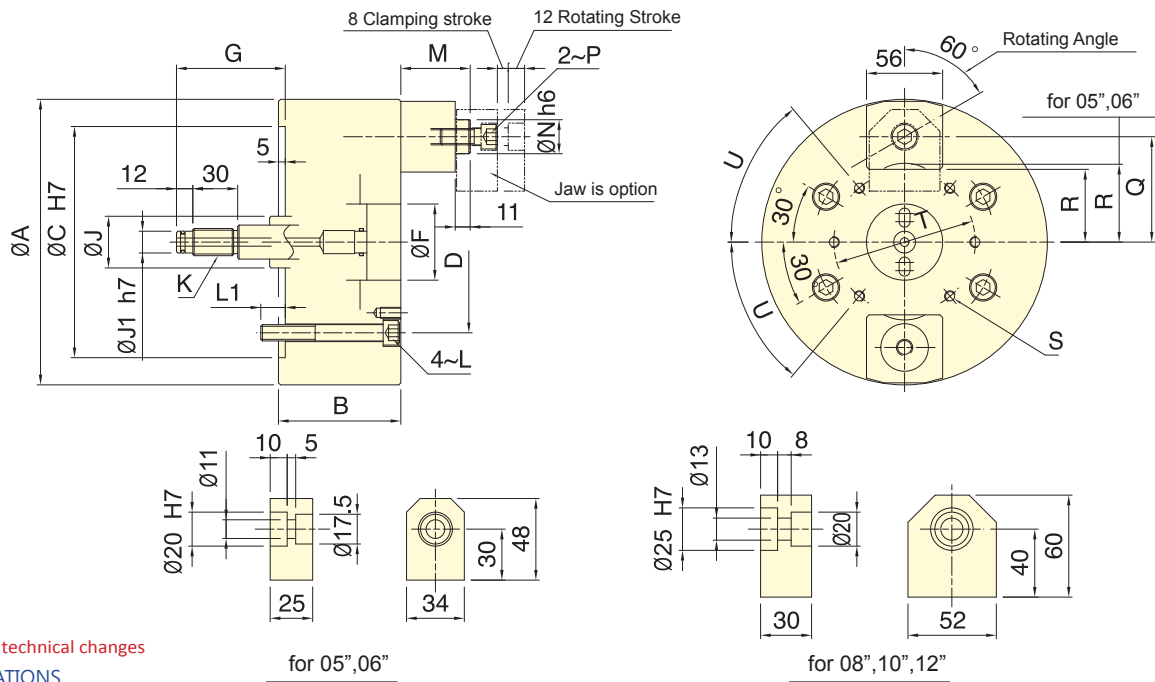




- Gripping at the end face and preventing deformation of workpiece.
- Suitable for thin wall workpiece processing.
- The gripping compensating mechanism can grasp the irregular surface workpieces well.
- Airtight pressure detect function is optional.



Subject to technical changes

SPECIFICATIONS

Model	Rotating stroke	Clamping stroke	Jaw's compensation	Chuck Dia.		Max. D.B. pull	Max. Clamping force	Max. speed	I Moment of inertia	Weight	Matching cyl.	Max. pressure
				Max.	Min.							
	mm	mm	mm	mm	mm	kN (kgf)	kN (kgf)	min ⁻¹ (r.p.m.)	kg·m ²	kg		MPa (kgf/cm ²)
2J-05	12	8	2	53	25	5.0(510)	4.0(408)	4000	0.015	9.0	RK-100 OR RK-100(N)	0.7(7)
2J-06	12	8	2	79	55	6.0(612)	5.0(510)	4000	0.035	9.8	RK-100 OR RK-100(N)	0.8(8)
2J-08	12	8	2	106	75	12.0(1224)	11.0(1122)	3500	0.12	20.3	RK-100 OR RK-100(N)	1.7(17)
2J-10	12	8	2.5	150	119	12.0(1224)	11.0(1122)	3500	0.28	30.7	RK-100 OR RK-100(N)	1.7(17)
2J-12	12	8	2.5	200	169	12.0(1224)	11.0(1122)	3000	0.52	41.2	RK-100 OR RK-100(N)	1.7(17)

DIMENSIONS

Model	A	B	C	D	F	G max.	G min.	J	J1	K
2J-05	135	86	110	82.6	40	75	55	25	9	M12x1.75
2J-06	165	86	140	104.8	45	75	55	28	12	M16x2
2J-08	210	90	170	133.4	56	80	60	38	16	M20x2.5
2J-10	254	95	220	171.4	56	75	55	38	16	M20x2.5
2J-12	304	95	220	171.4	56	75	55	38	16	M20x2.5

Model	L	L1	M max.	M min.	N	P	Q	R	S	T	U
2J-05	M10	15	56	36	20	M10	42.5	27	4~M6	50	30°
2J-06	M10	15	56	36	20	M10	57.5	40	4~M8	64	30°
2J-08	M12	18	71	51	25	M12	77.5	53.5	6~M8	104	50°
2J-10	M16	24	71	51	25	M12	99.5	75.5	6~M8	140	50°
2J-12	M16	24	71	51	25	M12	124.5	100.5	6~M8	190	50°